L37S Series

L03S Series

Application Manual



L37S D15M L37S D15M-A



 $L37S \square \square D15J$



L03S



L03S D15WM L03S D15WM-

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 $L03S \square \square D15WJ$

Overview

Both L03S series and L37S series are open-loop type and through type current sensors.

Their rated currents vary from 50A to 600A.

(L03S D15WJ L03S D15WM L03S D15WM-A is 50A to 800A)

Both the L37S and L03S series can be classified into three types according to the connector specifications shown in Table 1. For the L37S series, L03S D15WJ L03S D15WM L03S D15WM-A, the saturation current characteristics have been improved compared with the L03S series.

Model number	Cor	Remarks		
	Connecter	Connector	Connector	
	manufacturer	product number	terminal	
		/(Old product	Plating	
		number)	specification	
$L37S \square \square D15J$	JST	B4B-XH-A-G	Gold	Recommended
L03S==D15WJ				products: L37S
L37S000D15M	Molex	22-04-1041	Sn	series (L37S
L03SOOD15WM		/ (5045-04A)		series is the
$L03S \square \square D15$				successor model
L37SOOD15M-A	Molex	22-11-1041	Gold	of L03S series)
L03SOOD15WM-A		/ (5045-04AG)		
L03SDDD15-A				

Table 1: Series model number and connector specification

Characteristics

- · Through-type supply system of the current to be measured.
- · Open-loop-type circuit configuration.
- \cdot Connector-type input and output can be attached directly to a panel or to a bus bar.
- · Simple structure

Uses

- · General-purpose inverter
- · Motor drive
- · Generator
- · Electronic breaker

Format

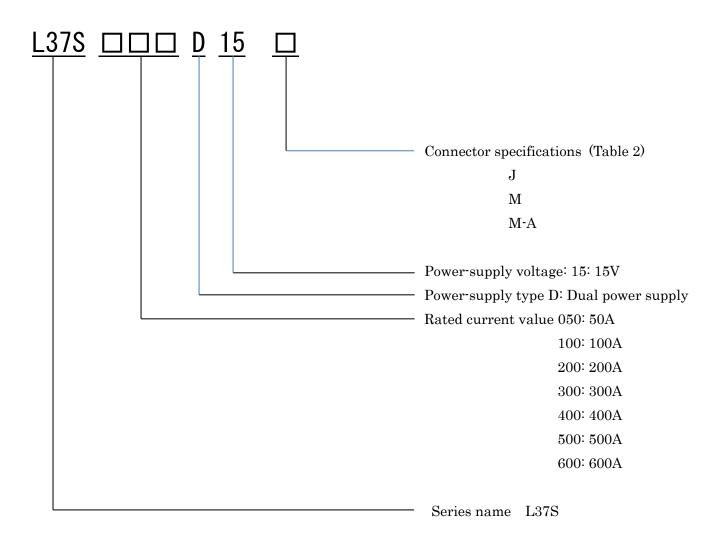


Table 2: L37S series	Specifications of connector an	d terminal plating
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Model number		Connecter specifications		
		Connecter	Connector product	Connector terminal
		manufacturer	number	Plating
			/(Old product number)	specification
L37SoooD15J	Standard	JST	B4B-XH-A-G	Gold
L37SDDD $15M$	Standard	Molex	22-04-1041	Sn
			/(5045-04A)	
L37SDDD15M-A	Build-to-order	Molex	22-11-1041	Gold
	manufacturing		/(5045-04AG)	

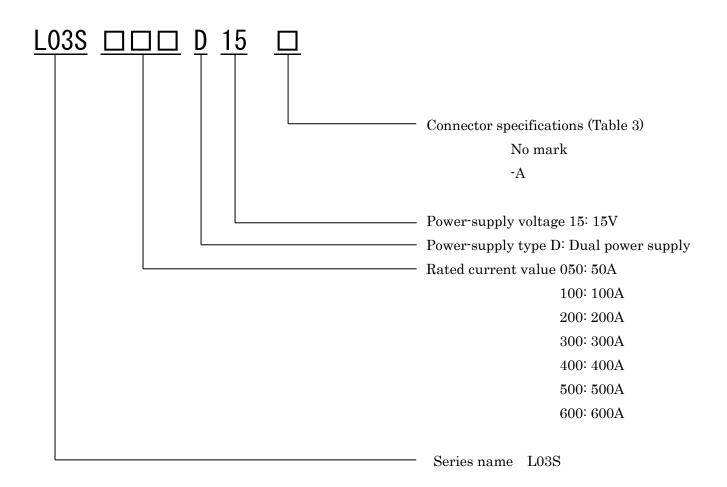


Table 3: L03S series	Specifications of connector	and terminal plating
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Model number		Connecter specifications		
		Connecter	Connector product	Connector terminal
		manufacturer	number	Plating
			/(Old product number)	specification
L03SoooD15	-	Molex	22-04-1041	Sn
			/(5045-04A)	
L03SnnnD15-A	Build-to-order	Molex	22-11-1041	Gold
	manufacturing		/(5045-04AG)	

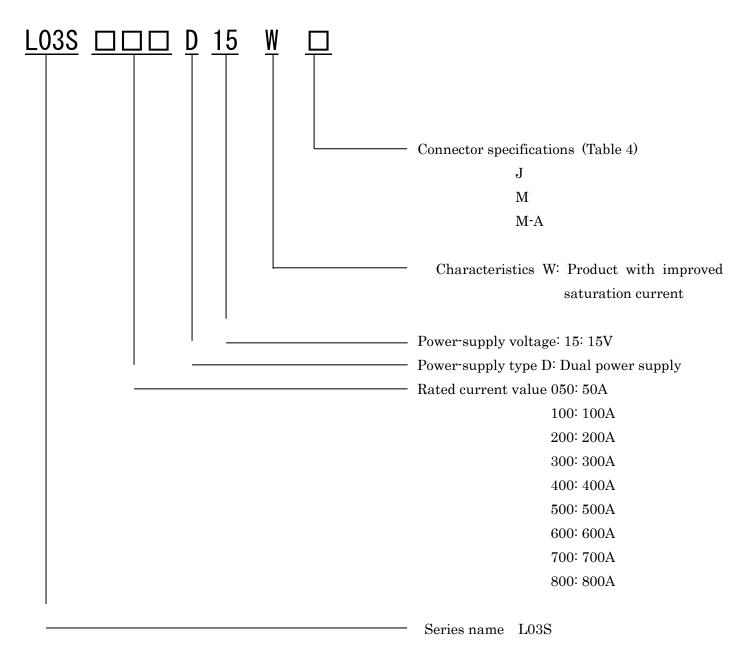


 Table 4: L03S series
 Specifications of connector and terminal plating

Model number		Connecter specifications		
		Connecter	Connector product	Connector terminal
		manufacturer	number	Plating
			/(Old product number)	specification
L03SnnnD15WJ	-	JST	B4B-XH-A-G	Gold
L03SnnnD15WM	-	Molex	22-04-1041	Sn
			/(5045-04A)	
L03SnnnD15WM-A	Build-to-order	Molex	22-11-1041	Gold
	manufacturing		/(5045-04AG)	

Block diagram (±15V Dual power-supply type)

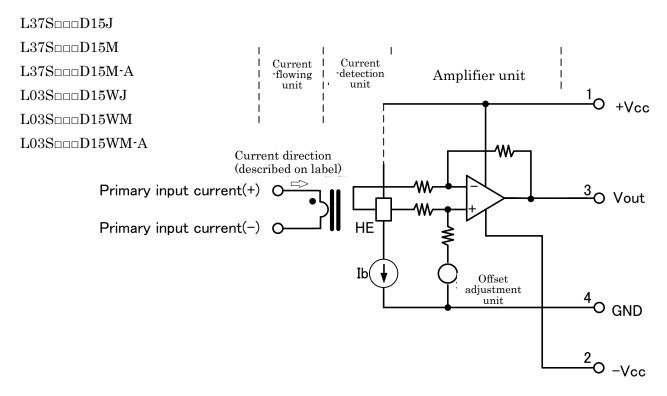


Fig. 1: L37S L03S series Internal block diagram (Excluding L03S D15 and L03S D15-A)

Terminal	Terminal name	Description	Remarks
number			
1	+Vcc	Positive voltage terminal of power-supply	
		voltage	
		Apply +12V or + 15V.	
2	-Vcc	Negative voltage terminal of	
		power-supply voltage	
		Apply -12V or -15V.	
3	Vout	Output terminal	*
4	GND	GND terminal	
	Primary current (+)	The plus side of the primary current	
		(measured current).	
		When the primary current flows in the	
		direction of the arrow (\Rightarrow) on the label,	
		the output voltage is output with positive	

	polarity to the output terminal (3).	
Primary current (-)	The minus terminal of the primary	
	current (measured current)	

* The standard value of output voltage is

$$Vout = G \times I + Vof$$
; $G \equiv \frac{4.0V}{If}$ If : Rated current Vof : Offset voltage

The standard value of the offset voltage is 0V.

$L03S \square \square \square D15$ L03SDDDD15-A

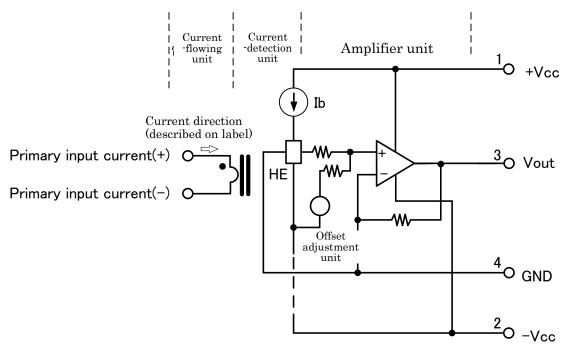


Fig. 2: L03S DD15 L03S DD15-A

Internal block diagram

Terminal	Terminal name	Description	Remarks	
number				
1	+Vcc	Positive voltage terminal of power-supply		
		voltage		
		Apply +15V.		
2	-Vcc	Negative voltage terminal of		
		power-supply voltage		
		Apply –15V.		
3	Vout 1	Output terminal	*	
4	GND	GND terminal		
	Primary current (+)	The plus side of the primary current		
		(measured current).		
		When the primary current flows in the		
		direction of the arrow (\Rightarrow) on the label,		
		the output voltage is output with positive		
		polarity to the output terminal (3).		
	Primary current (-)	The minus terminal of the primary		
		current (measured current)		

L37S L03S Description of operation

Current-detection unit

The current to be measured (primary input current) passes through the through-hole. The generated magnetic flux is focused by a core and applied to the magnetic-detection element (Hall element, HE).

The generated magnetic flux is proportional to the measured current I. The magnetic-detection element outputs a voltage proportional to the magnetic flux, i.e., provides an output voltage proportional to the current to the next-stage amplifier.

The current detector outputs a voltage up to the limit fixed by the rated current without saturation (refer to each catalog value). However, the linearity is guaranteed only up to the rated current value. (See also "amplifier unit" for the saturation current.)

Amplifier unit

This block amplifies the output voltage of the magnetic-detection element. The amplifier unit has the maximum output voltage limited by the power-supply voltage. Therefore, the amplifier unit may be saturated even when the current-detection unit of the preceding stage is not. The range that can be used without saturation for power-supply voltage ± 15 V is different from that for ± 12 V.

Because the output voltage of the magnetic-detection element is determined by factors such as the rated current value, etc., the gain in each product is precisely adjusted in the factory.

<u>Offset adjustment unit</u>

The offset voltage serves as a reference of the output voltage and is given by the output voltage when the current to be measured is 0A. The standard value of the offset voltage is 0V for the current sensor of dual power-supply. Possible deviation in the plus or minus direction owing to an initial deviation and temperature variations should be considered. (Please refer to the specifications table.)

The main origin of the deviation of the offset voltage from the standard value lies in the fact that the Hall element, HE, which is a magnetic sensing element, has an offset voltage. The offset voltage of the Hall element refers to the voltage output from the Hall element, which is minute but nonzero even in the absence of applied magnetic flux. A certain deviation of the offset voltage can arise in the amplifier unit instead of the Hall element. The offset adjustment unit has already been controlled in the factory in such a way that these offsets are globally canceled and fall within a predetermined range of deviation.

Current-flowing unit

The current-flowing part is used by passing a bus bar or electric wire through the through-hole in the main body. The current to be measured is supplied to the bus bar or the electric wire passing through the through-hole. The bus bar or electric wire generates heat owing to its own resistance component (copper

loss). Choose either a bus bar or electric wire in such a way that the temperature of the sensor does not exceed the specified value even when the ambient temperature is the allowable maximum value.

In addition to the copper loss caused by the penetrated bus bar and electric wire, heat is generated owing to iron loss (core loss) of the core built in the sensor. Each loss varies depending on conditions such as the magnitude, frequency, waveform, etc., of the current to be measured. The loss increases with the effective current value or with the dominant frequency component of the current to be measured. When the current contains high-frequency components other than those of the fundamental wave, iron loss further increases. Therefore, confirmation using an actual current is necessary.

■<u>Standard circuit</u>

L37S===D15J L37S===D15M L37S===D15M-A

L03S000D15WJ L03S000D15WM L03S000D15WM-A L03S000D15 L03S000D15-A

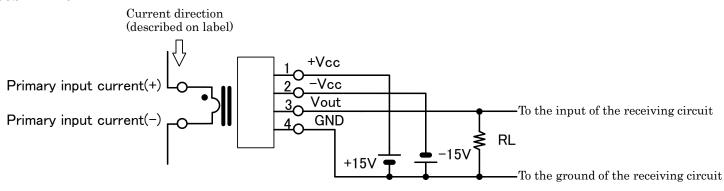


Fig. 3: L37S L03S Standard circuit

\square Description of Fig. 3

Basic operation

This current sensor converts a measured current into a voltage. The output voltage Vout (3) in Fig. 3 is output on the basis of the GND potential. When the current to be measured is 0, Vout (3) = 0V. When the current to be measured is in the plus direction (direction \Rightarrow of the label), Vout (3) becomes 0V + (voltage Vout (3)) and (3) are constant.

converted from the measured current). When the current to be measured is in the minus direction (direction opposite to \Rightarrow of the label), Vout (3) becomes 0V – (voltage converted from the measured current).

The standard value of the output voltage Vout corresponding to the current Iin to be measured is expressed by the following equation.

 $Vout = G \times Iin + Vof$; $G \equiv \frac{4.0V}{If}$ If: Rated current V of f Offset voltage Standard value is \mathcal{W}

 $RL = 10 \text{ k}\Omega$ in Fig. 3 is the equivalent resistance of the receiving circuit of the current sensor output Vout (3). The load resistance between the Vout terminal (3) and the GND potential (4) is standard 10 k Ω .

Effect of offset voltage

The offset voltage Vof is 0 ± 30 mV at maximum in the case of L37S050D15J under the condition of Ta = 25°C. An error within $\pm 0.75\%$ occurs when measuring the rated current. When measured current is three times the rated current, the influence of the offset voltage decreases to 1/3 and the error is compressed to within $\pm 0.25\%$. On the other hand, when the measured current is half the rated current, the error of the offset voltage ± 30 mV is within $\pm 1.5\%$ because the output voltage is 2.0V.

In order to minimize the error, it is necessary to select a sensor with a rated current suitable for the measured current.

If a sensor with a higher rated current than necessary is selected, the measurement error due to the offset voltage increases. In selecting the rated current, it is necessary to consider the capability of covering the peak value of the measured current, heat generated by the bus bar, and the core built in the sensor, etc. as well as the above conditions.

Application Circuit: Conversion circuit with reference voltage 2.5V

L37SDDD15J

L37S000D15M

- Can be converted to CPU reference voltage (2.5 V) with accuracy being maintained. -

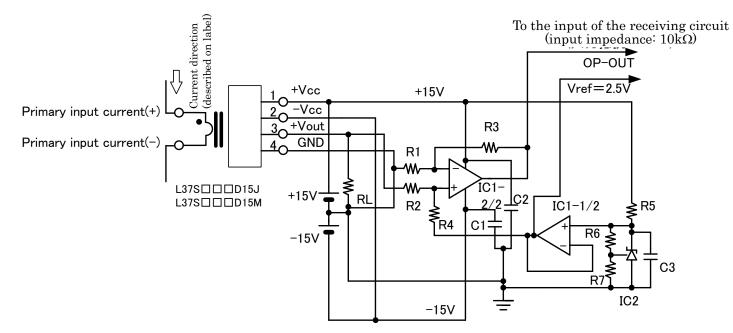


Fig. 4: Conversion circuit with reference voltage 2.5V

Table 9: Conversion circuit with reference voltage 2.5V

Symbol	Product name	Model number / Rating	Manufacturer	Remarks
C1, C2, C3	Ceramic capacitor	/0.1uF		
IC1	Integrated circuit	TL082	TI	
IC2	"	TL431	TI	
R1, R2	Fixed resistor	14.08kΩ		
R3, R4	"	$2.2 \mathrm{k}\Omega$		
R5	//	10kΩ		
R6	"	22Ω		
R7	"	10kΩ		
RL	Fixed resistor	$33\mathrm{k}\Omega$		

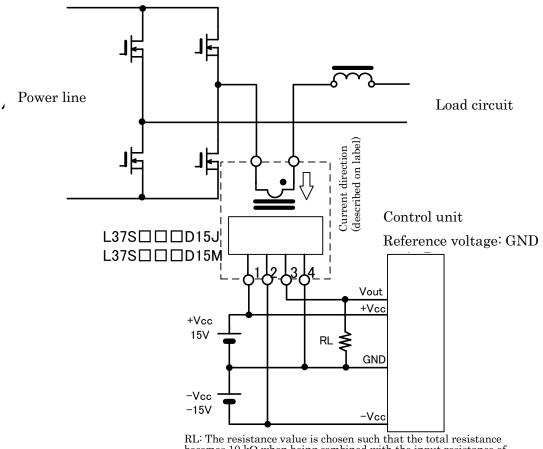
The output voltage Vout corresponding to the current Iin to be measured, as shown in Fig. 4, is expressed by the following equation.

 $Vout = G \times Iin + Vof$; $G \equiv \frac{0.625V}{If}$ If: Rated current $V \circ f$ Offset voltage Standard value is 2.5V

■Application circuit: Inverter current-detection circuit

 $L37S \square \square \square D15J$

 $L37S \square \square \square D15M$



becomes 10 k Ω when being combined with the input resistance of control unit.

The output voltage *Vout* corresponding to the current *lin* to be measured is expressed by the following equation.

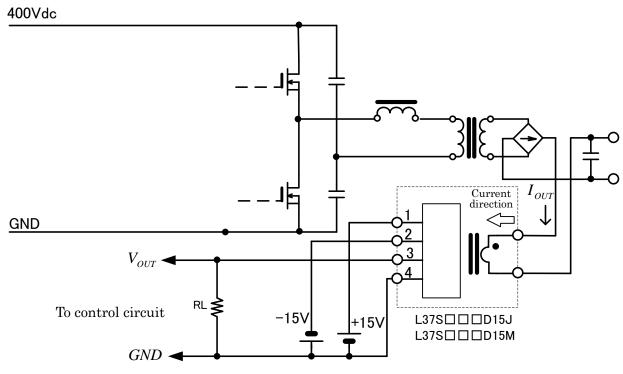
 $Vout = G \times Iin + Vof$; $G \equiv \frac{4.0}{If}$ If : Rated current V o; Offset voltage Standard value is 0V

Fig. 5: Inverter current-detection circuit

■Application Circuit: Overcurrent-detection circuit

L37SoooD15J

L37SoooD15M



RL: The resistance value is chosen such that the total resistance becomes 10 k Ω when being combined with the input resistance of control circuit.

The output voltage *Vout* corresponding to the current *lout* to be measured is given by the following equation.

 $Vout = G \times Iout + Vof$; $G \equiv \frac{4.0}{If}$ If: Rated current V o *f*Offset voltage Standard value is OV

Fig. 6: Overcurrent-detection circuit